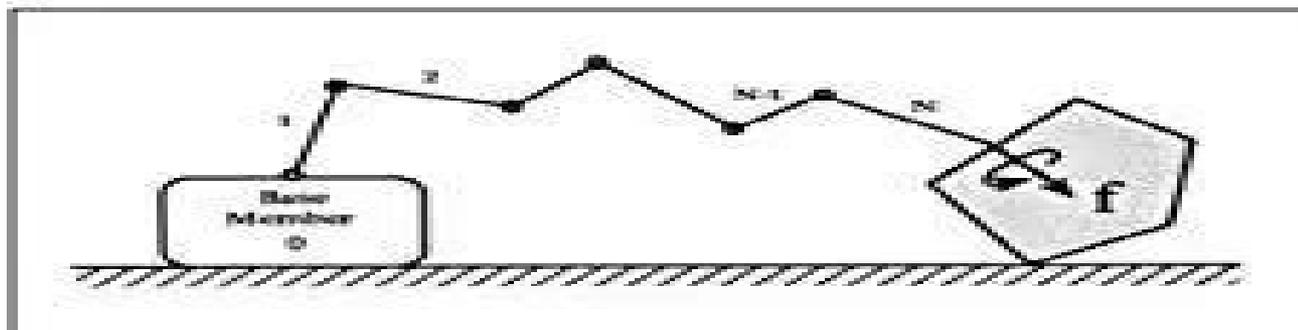

Efficient Dynamic Simulation of Robotic Mechanisms

Kathryn W. Lilly



Efficient Dynamic Simulation Of Robotic Mechanisms

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